

• Torque motor 40 Nm Nominal voltage AC/DC 24 V Control modulating 2...10 V • Position feedback 2...10 V

extended functionalities for adjusting dampers in technical building installations

• Air damper size up to approx. 8 m²

Technical data sheet Modulating rotary actuator fail-safe and

GK24A-SR



Technical data

| Electrical data | Nominal voltage | AC/DC 24 V |
|-----------------|------------------------------------|--|
| | Nominal voltage frequency | 50/60 Hz |
| | Nominal voltage range | AC 19.228.8 V / DC 21.628.8 V |
| | Power consumption in operation | 11 W |
| | Power consumption in rest position | 3 W |
| | Power consumption for wire sizing | 21 VA |
| | Connection supply / control | Cable 1 m, 4 x 0.75 mm ² |
| | Parallel operation | Yes (note the performance data) |
| Functional data | Torque motor | 40 Nm |
| | Operating range Y | 210 V |
| | Input Impedance | 100 kΩ |
| | Position feedback U | 210 V |
| | Position feedback U note | Max. 0.5 mA |
| | Setting fail-safe position | 0100%, adjustable in increments of 10% (POP rotary knob on 0 corresponds to left end stop) |
| | Bridging time (PF) | 2 s |
| | Position accuracy | ±5% |
| | Direction of motion motor | selectable with switch 0/1 |
| | Direction of motion note | Y = 0 V: At switch position 0 (ccw rotation) / 1 (cw rotation) |
| | Direction of motion fail-safe | selectable with switch 0100% |
| | Manual override | with push-button |
| | Angle of rotation | Max. 95° |
| | Angle of rotation note | can be limited on both sides with adjustable mechanical end stops |
| | Running time motor | 150 s / 90° |
| | Running time fail-safe | 35 s / 90° |
| | Sound power level, motor | 53 dB(A) |
| | Sound power level, fail-safe | 61 dB(A) |
| | Mechanical interface | Universal shaft clamp reversible 1226.7 mm |
| | Position indication | Mechanically, pluggable |
| Safety data | Protection class IEC/EN | III, Safety Extra-Low Voltage (SELV) |
| | Power source UL | Class 2 Supply |
| | Degree of protection IEC/EN | IP54 |
| | Degree of protection NEMA/UL | NEMA 2 |
| | Enclosure | UL Enclosure Type 2 |
| | EMC | CE according to 2014/30/EU |
| | Certification IEC/EN | IEC/EN 60730-1 and IEC/EN 60730-2-14 |



Technical data sheet

| Safety data | UL Approval | cULus according to UL60730-1A, UL60730-2-14 and CAN/CSA E60730-1 The UL marking on the actuator depends on the production site, the device is UL-compliant in any case | |
|-------------|--|--|--|
| | Mode of operation | Туре 1.АА | |
| | Rated impulse voltage supply / control | 0.8 kV | |
| | Pollution degree | 3 | |
| | Ambient humidity | Max. 95% RH, non-condensing | |
| | Ambient temperature | -3050°C [-22122°F] | |
| | Storage temperature | -4080°C [-40176°F] | |
| | Servicing | maintenance-free | |
| Weight | Weight | 1.9 kg | |
| Terms | Abbreviations | POP = Power off position / fail-safe position PF = Power fail delay time / bridging time | |
| | | | |

Safety notes



- This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the device and that it is ensured that the ambient conditions remain within the thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section, the design, the installation situation and the ventilation conditions must be observed.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

Product features

Mode of operation

The actuator moves the damper to the desired operating position at the same time as the integrated capacitors are charged. Interrupting the supply voltage causes the damper to be rotated back into the fail-safe position by means of stored electrical energy.

The actuator is connected with a standard control signal of 0...10 V and drives to the position defined by the control signal. Measuring voltage U serves for the electrical display of the damper position 0...100% and as a control signal for other actuators.

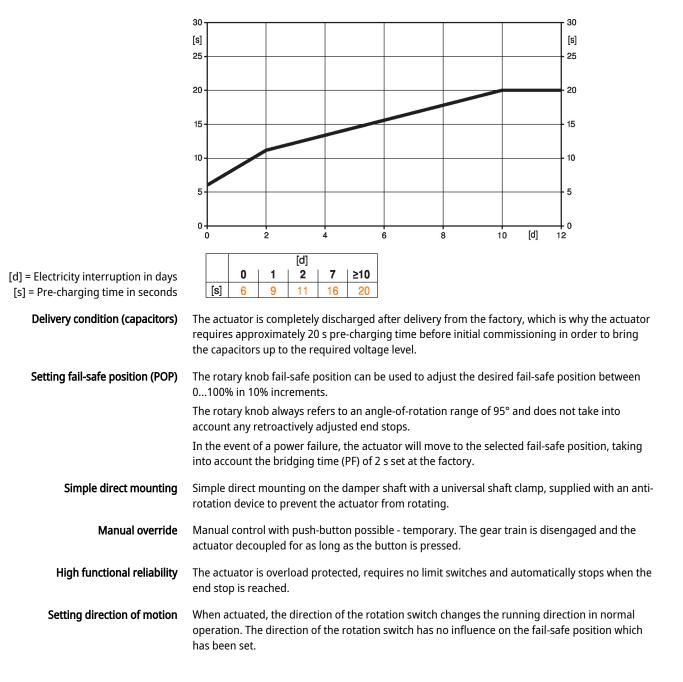


Technical data sheet

Pre-charging time (start up)

The capacitor actuators require a pre-charging time. This time is used for charging the capacitors up to a usable voltage level. This ensures that, in the event of a power failure, the actuator can move at any time from its current position into the preset fail-safe position. The duration of the pre-charging time depends mainly on how long the power was interrupted.

Typical pre-charging time







| Electrical accessories | Description | Туре |
|------------------------|---|----------|
| | Auxiliary switch 1 x SPDT add-on | S1A |
| | Auxiliary switch 2 x SPDT add-on | S2A |
| | Feedback potentiometer 140 Ω add-on | P140A |
| | Feedback potentiometer 200 Ω add-on | P200A |
| | Feedback potentiometer 500 Ω add-on | P500A |
| | Feedback potentiometer 1 k Ω add-on | P1000A |
| | Feedback potentiometer 2.8 kΩ add-on | P2800A |
| | Feedback potentiometer 5 k Ω add-on | P5000A |
| | Feedback potentiometer 10 k Ω add-on | P10000A |
| | Adapter for auxiliary switch and feedback potentiometer | Z-SPA |
| | Signal converter voltage/current 100 kΩ Supply AC/DC 24 V | Z-UIC |
| | Positioner for wall mounting | SGA24 |
| | Positioner for built-in mounting | SGE24 |
| | Positioner for front-panel mounting | SGF24 |
| | Positioner for wall mounting | CRP24-B1 |
| Mechanical accessories | Description | Туре |
| | Actuator arm for standard shaft clamp | AH-GMA |
| | Damper crank arm Slot width 8.2 mm, clamping range Ø1425 mm | KH10 |
| | Mounting kit for linkage operation for flat installation | ZG-GMA |
| | * Adapter Z-SPA | |
| | It is imperative that this adapter will be ordered if an auxiliary switch or a feedback potentiometer is required and if at the same time the shaft clamp is installed on the rear side | |

Electrical installation



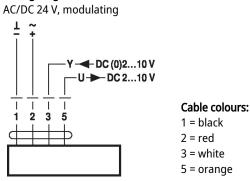
Supply from isolating transformer.

the actuator (e.g. with short shaft installation).

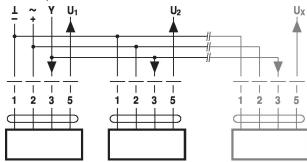


Parallel connection of other actuators possible. Observe the performance data.

Wiring diagrams



Parallel operation



Notes

• A maximum of eight actuators can be connected in parallel. • Parallel operation is permitted only on non-connected axes. • Do not fail to observe performance data with parallel operation.



2 3

1

U

5

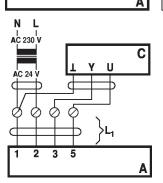
Technical data sheet

A = Actuator

C = Control unit (controlling unit) L1 = Connecting cable of the actuator L2 = Customer cable Ltot = Maximum signal cable length

Note:

When several actuators are connected in parallel, the maximum signal cable length must be divided by the number of actuators.



С

2.50 mm² \leq 100 m A = Actuator

C = Control unit (controlling unit) L1 = Connecting cable of the actuator

 $\mathsf{L}_{tot} = \mathsf{L}_1 + \mathsf{L}_2$

DC

≤5 m

≤8 m

≤12 m

≤20 m

AC

≤30 m

≤40 m

≤70 m

Note:

 L_2

1/~

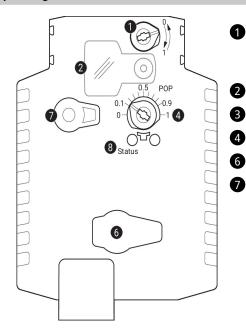
0.75 mm²

1.00 mm²

1.50 mm²

There are no special restrictions on installation if the supply and the data cable are routed separately.

Operating controls and indicators



1 Direction of rotation switch

Switch over:

Direction of rotation changes

- 2 Cover, POP button
- **3** POP button
- 4 Scale for manual adjustment
- 6 (no function)
 - Manual override button

Press button:Gear train disengages, motor stops, manual override possibleRelease button:Gear train engages, standard mode

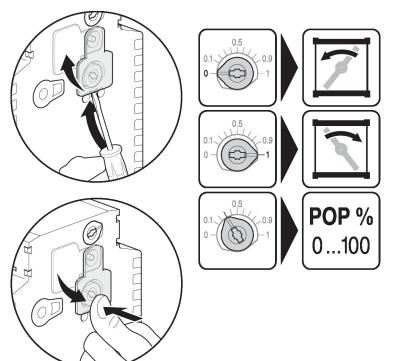
LED displays

| green 8 | Meaning / function |
|----------|------------------------------|
| On | Operation OK |
| Flashing | POP function active |
| Off | - Not in operation |
| | - Pre-charging time SuperCap |
| | - Fault SuperCap |



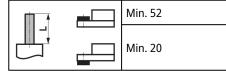
Technical data sheet

Setting emergency setting position (POP)



Dimensions

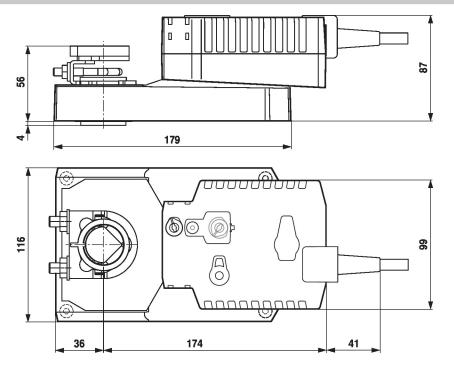
Spindle length



Clamping range

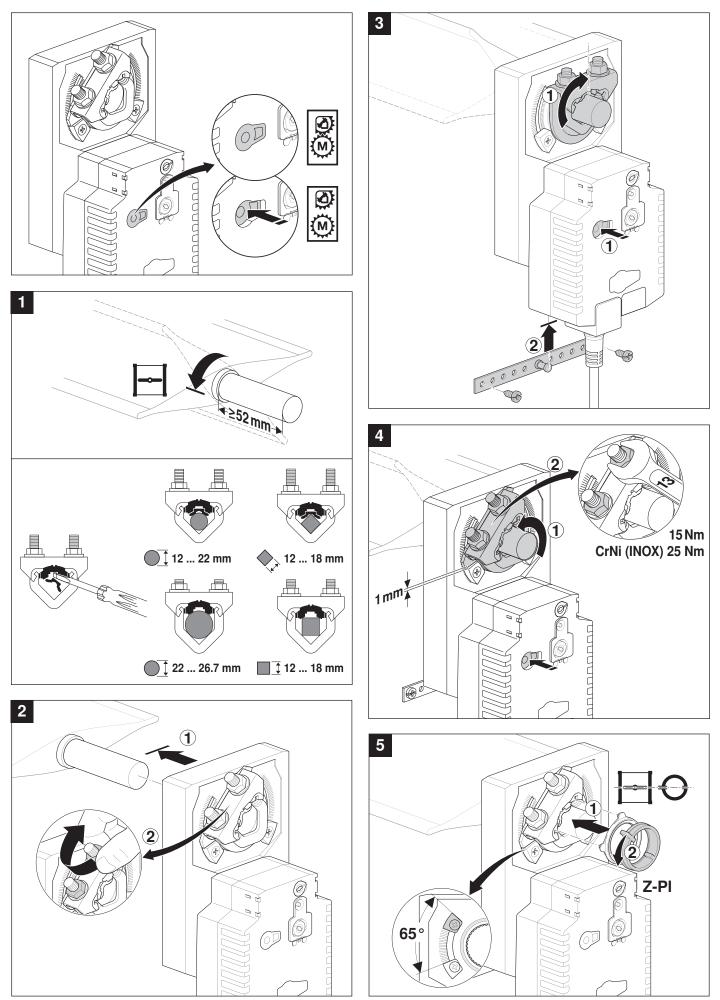
| 01 | |
|--------|------|
| 1222 | 1218 |
| 01 | T. |
| 2226.7 | 1218 |

*Option: Shaft clamp mounted below: If an auxiliary switch or a feedback potentiometer is used the adapter Z-SPA is required.



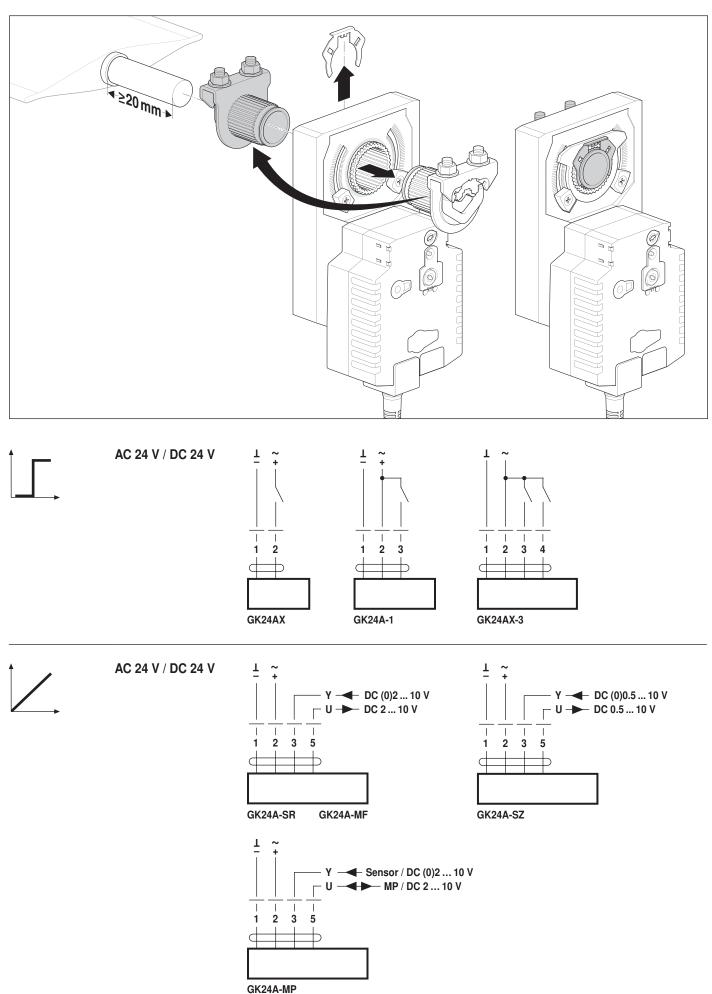


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